

Today's Satellite

4/1/08

Olympus

- ~~Comsat~~ Communications satellite.
- launched in 1989.
- earth crosses
- control - moment - gyros.
- damage to the solar array drive motors.
- earth horizon sensors ~~was~~ worn out
- used ground signals for horizon sensor.
- miss a beacon. \rightarrow attempted sun pointing.
- satellite went dead (tumbling)
- 75 days later, re-acquired the satellite.
- satellite struck by perseid meteors.

$$y + ky = u$$

$$u(t) = \int_{-\infty}^{\infty} u(\tau) \delta(t - \tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} u(\tau) h(t - \tau) d\tau = u * h = h * u$$

$$u(t) = e^{st} \quad y = H(s) e^{st}$$

$$H(s) = \int_{-\infty}^{\infty} e^{-s\tau} h(\tau) d\tau$$

$$u(t) = a \cos \omega t$$

$$y(t) = a |H| \cos(\omega t + \angle H)$$

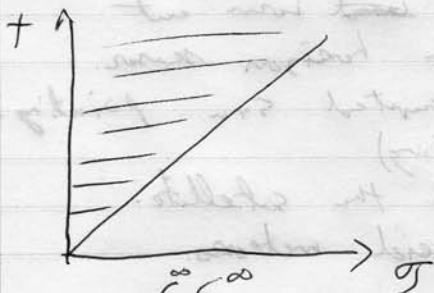
Laplace Transform

$$F(s) = \int_0^{\infty} e^{-s\tau} f(\tau) d\tau$$

$$y(s) = \int_0^{\infty} e^{-st} y(t) dt$$

$$= \int_0^{\infty} e^{-st} \int_0^t u(\sigma) h(t-\sigma) d\sigma dt$$

$$= \int_0^{\infty} \int_0^t e^{-st} u(\sigma) h(t-\sigma) d\sigma dt$$



$$= \int_0^{\infty} \int_{\sigma}^{\infty} e^{-st} u(\sigma) h(t-\sigma) dt d\sigma$$

$$\Rightarrow t - \sigma \rightarrow t = v + \sigma$$

$$= \int_0^{\infty} \int_0^{\infty} e^{-s(v+\sigma)} u(\sigma) h(v) dv d\sigma$$

$$= \int_0^{\infty} e^{-sv} h(v) dv \int_0^{\infty} e^{-s\sigma} u(\sigma) d\sigma$$

$$= H(s) U(s)$$

$$\therefore y(t) = \mathcal{L}^{-1} (H(s) U(s))$$

$$\mathcal{L}(y) = \mathcal{L}\left(\frac{dy}{dt}\right) = \int_0^{\infty} e^{-st} \left(\frac{dy}{dt}\right) dt$$

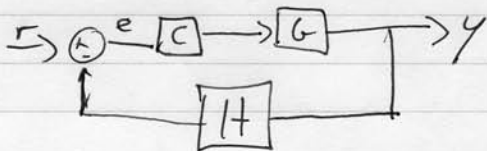
$$\int v du = uv - \int u dv$$

$$\mathcal{L}(y) = y(t) e^{-st} \Big|_0^{\infty} + \int_0^{\infty} s y(t) e^{-st} dt$$

$$= -y(0) + s Y(s)$$

$$Y(s) = \frac{y(0)}{s+k} + \frac{U(s)}{s+k}$$

$$h(t) = \mathcal{L}^{-1}\left(\frac{1}{s+k}\right) = e^{-kt}$$



$$y = CGe = CG(r - Hy)$$

$$\frac{y}{r} = \frac{CG}{1 + CGH}$$

$$e = r - Hy = r H (CGe)$$

$$\frac{e}{r} = \frac{1}{1 + CGH}$$

Final Value Theorem

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s)$$

Axisymmetric Spin stabilized.

cf

$$M_3 = J_3 \dot{\omega}_3$$

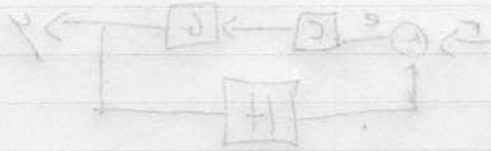
$$M_3 = -k_p \omega_3 + u(t)$$

$$J_3 \dot{\omega}_3 + k_p \omega_3 = u(t)$$

$$\rightarrow \begin{cases} \dot{y} + k = u \\ \text{same system.} \end{cases}$$

$$\frac{(s)N}{s+2} + \frac{(s)N}{s+2} = \frac{N}{s}$$

$$2N = (s)N = (s)N$$



$$y = C G = C G (s - H)$$

$$\frac{y}{u} = \frac{C G}{1 + C G H}$$

$$e = u - y = u - C G (s - H)$$

$$\frac{e}{u} = \frac{1}{1 + C G H}$$

Final Value Theorem

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s)$$