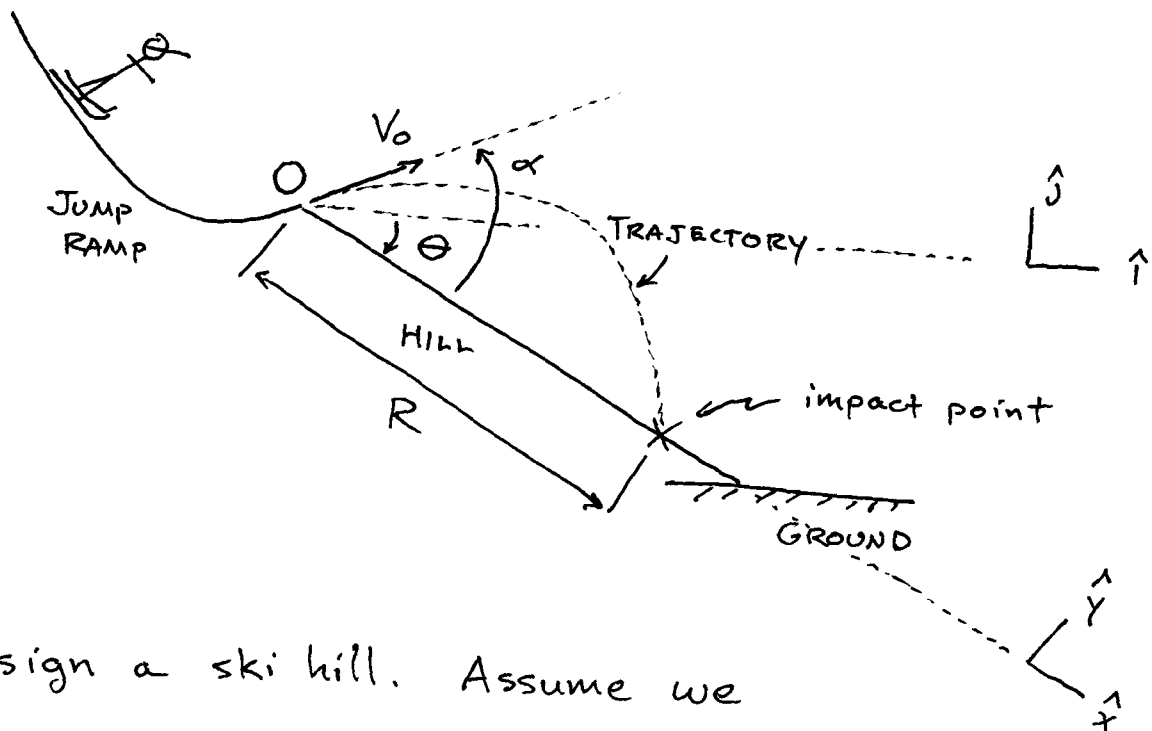


Example: planar motion, constant acceleration,
rotated coordinate system



Design a ski hill. Assume we are given the maximum initial velocity v_0 , the angle θ of the hill, and the length R of the hill (before a jumper hits the "ground"). Choose the ramp angle α so the jumper lands at R . (Assume constant acceleration $\vec{a} = -g\hat{j}$.)

A choice that makes things easier: use a coordinate system \hat{x}, \hat{y} aligned with the hill.

Notice that $\hat{j} = -\sin\theta \hat{x} + \cos\theta \hat{y}$.

$$\text{So } \vec{a} = -g\hat{j} = g\sin\theta \hat{x} - g\cos\theta \hat{y}.$$

$$\vec{v} = (v_0 \cos\alpha + g\sin\theta t) \hat{x} + (v_0 \sin\alpha - g\cos\theta t) \hat{y}$$

$$\vec{r} = (v_0 \cos\alpha t + g\sin\theta \frac{t^2}{2}) \hat{x} + (v_0 \sin\alpha t - g\cos\theta \frac{t^2}{2}) \hat{y}$$

WHEN does the skier hit? When $\vec{r} \cdot \hat{y} = 0$.

$$v_0 \sin\alpha t - g\cos\theta \frac{t^2}{2} = 0$$

$$t = 0 \quad \text{or} \quad t = \frac{2v_0 \sin\alpha}{g \cos\theta}$$

WHERE does the skier hit? At $\vec{r} \cdot \hat{x} = R$.

$$R = v_0 \cos\alpha \left(\frac{2v_0 \sin\alpha}{g \cos\theta} \right) + \frac{g\sin\theta}{2} \left(\frac{4v_0^2 \sin^2\alpha}{g^2 \cos^2\theta} \right)$$

$$\Rightarrow R = \left(\frac{2v_0^2}{g} \right) \left(\frac{\sin\alpha \cos\alpha}{\cos\theta} + \frac{\sin^2\alpha \sin\theta}{\cos^2\theta} \right)$$

At this point, we might want to solve numerically for α , given (for example)

$$R = 15 \text{ meters} \quad g = 9.8 \frac{\text{meters}}{\text{second}^2}$$

$$\theta = 30^\circ \quad v_0 = 10 \frac{\text{meters}}{\text{second}}$$

We find $\alpha = 34^\circ$ or $\alpha = 86^\circ$. Did you expect to have a choice? Since you do, which angle might you choose? What if you wanted the jumper's velocity normal to the hill at impact to be minimized? Is it possible to make this velocity zero by changing θ ? What if you wanted to maximize R ?