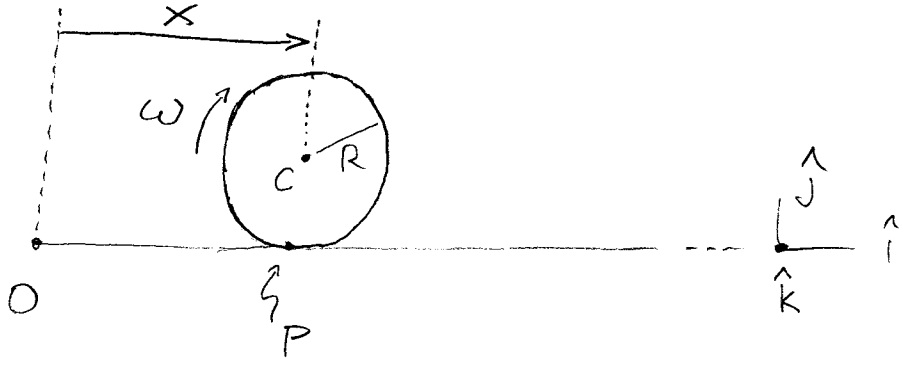


AE 252 (Spring 2007)

Bretl
3/27/07

Example: wheels



- If a wheel turns at ω rad/sec clockwise and rolls without slipping, how fast is its center (point C) moving?
- "Rolls without slipping" \rightarrow The relative velocity of the contact point P with respect to the ground is zero.
- NOTE: The "contact point" is the point on the wheel that is instantaneously in contact with the ground — this point changes!
- Here, the ground is not moving. So $\vec{v}_P = 0$ when P contacts the ground.

(6)

We just derived $\overset{F}{\vec{v}}_P = \overset{F}{\vec{v}}_C + \overset{F}{\vec{\omega}}^B \times \vec{r}_{P/C}$.

$$\overset{F}{\vec{v}}_P = 0$$

$$\overset{F}{\vec{v}}_C = \dot{x} \hat{i} \quad \leftarrow \left\{ \vec{r}_C = x \hat{i} + R \hat{j} \right.$$

$$\overset{F}{\vec{\omega}}^B = -\omega \hat{k}$$

$$\vec{r}_{P/C} = -R \hat{j} \quad \leftarrow \text{at the instant } P \text{ contacts the ground}$$

So ...

$$0 = \dot{x} \hat{i} + (-\omega \hat{k} \times -R \hat{j})$$

$$= \dot{x} \hat{i} - R\omega \hat{i}$$

$$\Rightarrow \boxed{\dot{x} = R\omega} \quad \leftarrow \text{so } \overset{F}{\vec{v}}_C = R\omega \hat{i}.$$

In your homework you will examine the velocity of other points on the wheel.